

Mobile Location Prediction in Spatio-Temporal Context

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Data Mining and Machine Learning Lab



Mobile Location Prediction



- Applications:
- Mobile Advertising
- Traffic Planning
- User oriented coupon dispersion
- Disaster Relief
- Challenges:
 - **Over-fitting** Long spatial-temporal trajectories with massive n-gram spatial patterns and sparse temporal patterns, smoothing techniques are indispensable.
- Integration Seek a good way to integrate both spatial information and temporal information.





Problem Statement



Given a user with a series of his historical visits in a previous time section, and a context of the latest visit location with the time of the next visit, the location prediction problem in Nokia Mobile Data Challenge can be described as finding the probability of

$$p(v_i = l \mid t_i = t, v_{i-1} = l_k)$$

Where

 $v_i = l$: the i-th visit at location I;

 $t_i = t$: the i-th visit happens at time t;

set as the "ending time of current visit"

 $v_{i-1} = l_k$: the (i-1)-th visit happened at location l_k .





Problem Statement



Using Bayes' rule,

$$p(v_{i} = l | t_{i} = t, v_{i-1} = l_{k})$$

$$= \frac{p(v_{i} = l, t_{i} = t | v_{i-1} = l_{k})}{p(t_{i} = t)}$$

$$\propto p(v_{i} = l, t_{i} = t | v_{i-1} = l_{k})$$

$$= p(t_{i} = t | v_{i} = l, v_{i-1} = l_{k})p(v_{i} = l | v_{i-1} = l_{k})$$

$$= p(t_{i} = t | v_{i} = l)p(v_{i} = l | v_{i-1} = l_{k})$$

$$= p(t_{i} = t | v_{i} = l, v_{i-1} = l_{k}) = p(t_{i} = t | v_{i} = l)$$

Consider $p(t_i = t | v_i = l, v_{i-1} = l_k) = p(t_i = t | v_i = l)$ under the assumption that the probability of current visit time is only relevant to the current visit location.





Problem Statement

$$p(v_{i} = l | t_{i} = t, v_{i-1} = l_{k})$$

= $p(t_{i} = t | v_{i} = l) p(v_{i} = l | v_{i-1} = l_{k})$

Temporal Constraint

Spatial Prior

The probability of the i-th visit happening at time t, observing that the i-th visit location is l.

The probability of next visit at location I given the current visit at I_k





Spatial Prior

- **Two properties of spatial prior** $p(v_i = l | v_{i-1} = l_k)$
- Power Law Distribution
- People tend to go to few places many times, and many places few times.
- Short Term Effect
- The current visit location is more relevant to the latest visit than the older visit. Correspondences between language and LBSN modeling

Language Modeling		LBSN Modeling		
Corpus		Check-in collection		
Document		Individual check-ins		
	Paragraph		Monthly check-in sequence	
Document	Sentence	Check-in	Weekly check-in sequence	
Structure	Phrase	Structure	Daily check-in sequence	
	Word		Check-in location	

[Gao et al. Exploring Social-Historcal Ties on Location-Based Social Networks. ICWSM 2012]





Spatial Prior

✤ Hierarchical Pitman-Yor (HPY) Language Model to generate the spatial prior $p(v_i = l | v_{i-1} = l_k)$ (HPY spatial prior) > Generate the probability of next location based on an

observation of historical visiting sequence.

- Consider a combination of all the n-gram patterns in the previous visits with various pattern weights.
- > The latest visit has higher weight than the older visit.

[Gao et al. Exploring Social-Historcal Ties on Location-Based Social Networks. ICWSM 2012]





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Temporal Constraint:

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$$p(t_i = t | v_i = l)$$

$$= p(h_i = h, d_i = d | v_i = l)$$

$$= p(h_i = h | v_i = l) p(d_i = d | v_i = l)$$
Hourly Constraint
$$Daily Constraint$$
h: Hour of the day, i.e., 10:00am, 3:00pm
d: Day of the week, i.e., Monday, Sunday





Compute $p(h_i = h | v_i = l)$ and $p(d_i = d | v_i = l)$

> For a visit location I that has happened at h (d) in the previous visits, it's easy to get $p(h_i = h | v_i = l)$ and $p(d_i = d | v_i = l)$

For a visit location I that has not happened at h (d) in the previous visits (majority part in the training set),

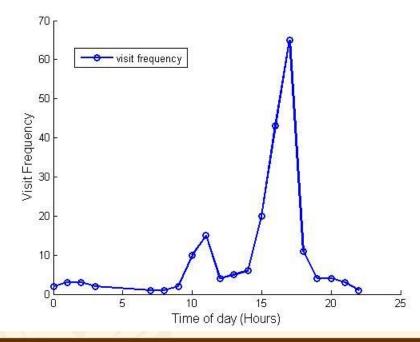
how to compute?

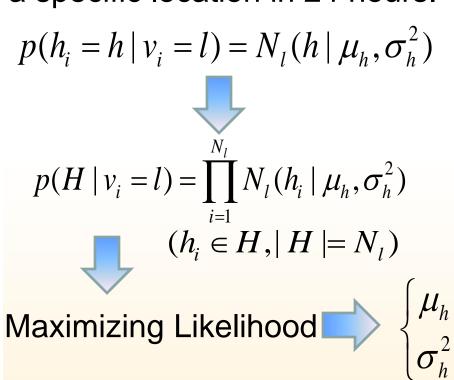




Compute $p(h_i = h | v_i = l)$ and $p(d_i = d | v_i = l)$

> Distribution of a user's visits at a specific location in 24 hours. (user id: 013; place id: 3) $p(h - h|y - l) - N(h|y - \sigma^2)$

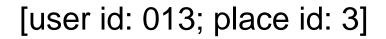


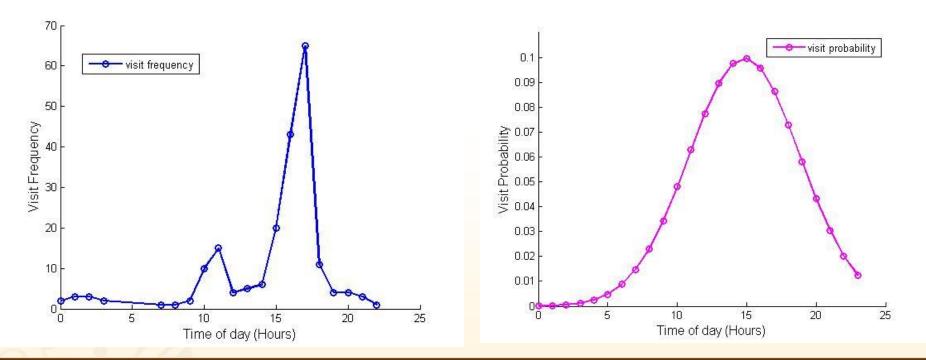






Curve Fitting:









Location Prediction

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Probability of visiting location I at time t with the latest visit at Ik

$$p(v_{i} = l | t_{i} = t, v_{i-1} = l_{k})$$

$$= p(v_{i} = l | v_{i-1} = l_{k})p(h_{i} = h | v_{i} = l)p(d_{i} = d | v_{i} = l)$$

$$= p(v_{i} = l | v_{i-1} = l_{k})N_{l}(h | \mu_{h}, \sigma_{h}^{2})N_{l}(d | \mu_{d}, \sigma_{d}^{2})$$

$$HPY Prior Gaussian Gaussian$$

$$HPY Prior Hour-Day Model (HPHD)$$







Experiment Setting
For Submission:
Training set: Set A
Testing set: Set C (no ground truth)
Number of users: 80

For Evaluation

Divide set A into training and testing parts.

Testing set: Toy data provided by Nokia with 3373 unknown locations.

Training set: For each user, all the visits in set A that happened before the visits in testing set.





- - Baseline Methods (Spatial Family)
 - 1. Most Frequent Visit Model (MFV) Consider the most frequent visited location
 - Order-1 Markov Model (OMM) Consider the most frequent two-gram pattern with the latest visit as context.
 - 3. Fallback Markov Model A combination of MFV and OMM
 - 4. HPY Prior Model (HP) Consider the HPY prior only to predict the next location.





- Baseline Methods (Temporal Family)
- Most Frequent Hourly Model (MFH) Predict the next visit at time h as the most frequent visit location at h in previous visits.

- Most Frequent Daily Model (MFD) Predict the next visit at time d as the most frequent visit location at d in previous visits.
- 7. Most Frequent Hour-Day Model (MFHD) A combination of MFH and MFD (by mutiplying)





Baseline Methods (Spatio-Temporal family)

- 8. HPY Prior Hourly Model (HPH) Consider the HPY prior and hourly information.
- 9. HPY Prior Daily Model (HPD) Consider the HPY Prior and daily information.
- Proposed Method (Spatio-Temporal family) HPY Prior Hour-Day Model (HPHD) Consider the HPY prior, hourly information, and daily information.





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Table 1: Location Prediction Results

	Models	Correct No.	Accuracy
	MFV	1148	0.3402
Spatial-based	OMM	1466	0.4345
Spanal-Dased	FMM	1583	0.4692
	HP	1610	0.4772
	MFH	1462	0.4333
Temporal-based	MFD	1156	0.3426
	MFHD	1538	0.4558
	HPH	1680	0.4979
Spatio-temporal	HPD	1583	0.4692
	HPHD	1705	0.5053

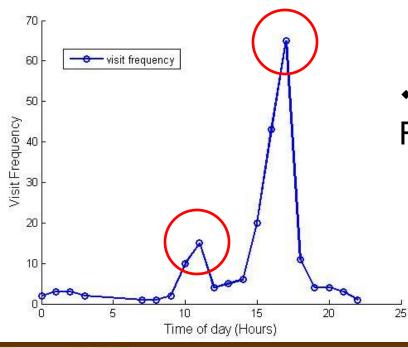




Conclusions and Future Work

Gaussian Distribution with Two Peaks
 An alternative version of HPHD. (AHPHD)
 Not stable consitiute to peak detection

> Not stable, sensitive to peak detection.



Five Submissions FHD, HP, HPH, HPHD, AHPHD





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Questions?



